



# Prediction of Minor Loss Coefficient at Suction Inlet of a Cutter Suction Dredge

*Joshua M. Lewis and Dr. Robert E.  
Randall*

Presented by: *Joshua M. Lewis*  
*LT, CEC, USN*  
*United States Navy*  
*Texas A&M University ('14)*





*Dwight Look College of*

**ENGINEERING**  
TEXAS A&M UNIVERSITY

# OUTLINE

- Research Objectives
- Experimental Setup
- Data Collection
- Results
- Conclusions
- Recommendations

Primary:

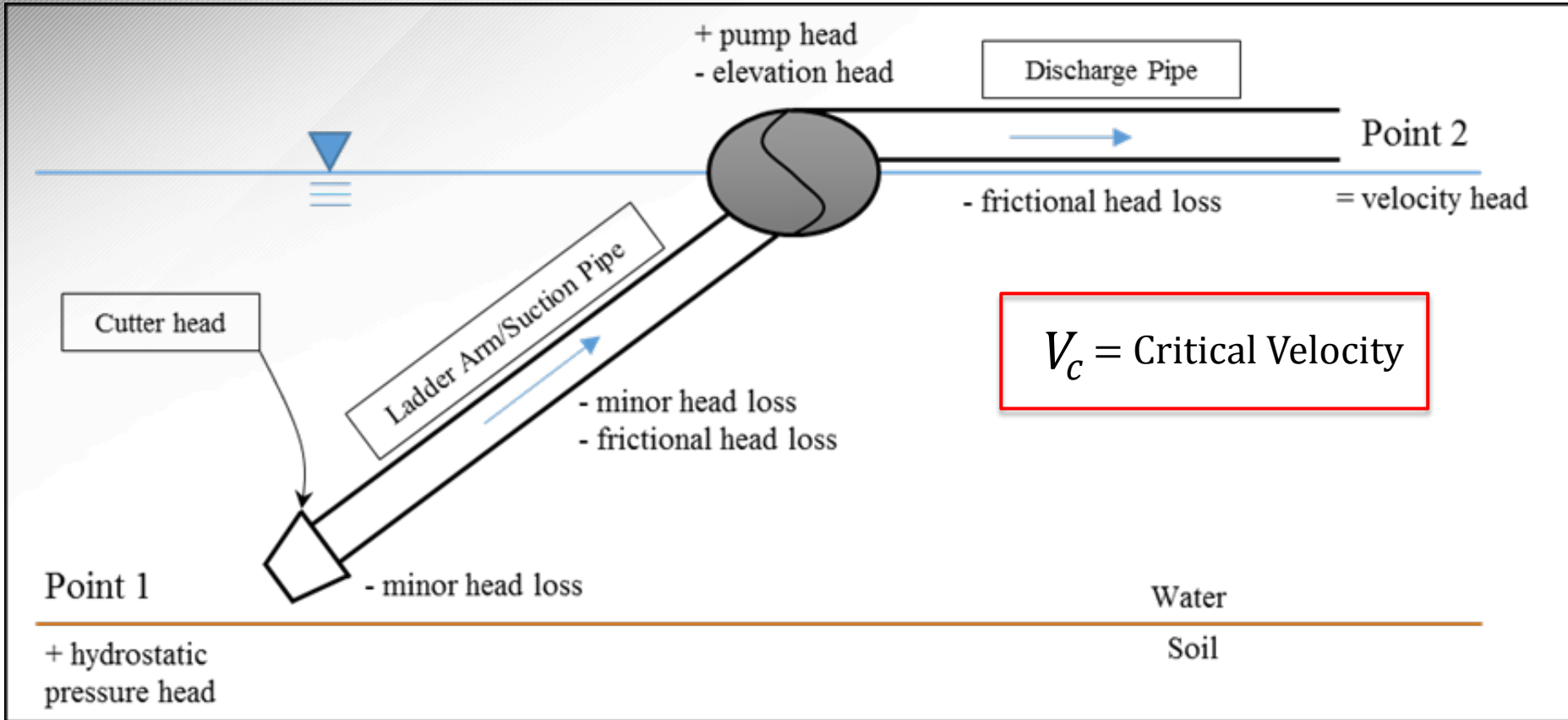
- Quantify and predict a fixed screen's minor loss coefficient ( $k$ ) while changing:
  - Cutter head rotational speed,  $\Omega$  [RPM]
  - Ladder arm swing speed,  $V_L$  [in/s]
  - Screen Opening Percentage,  $\beta$  [Area of Openings/Area of Suction Mouth]
- Can  $k$  be expressed as:  $k = f(\Omega, \beta, V_L)$  ?

Secondary:

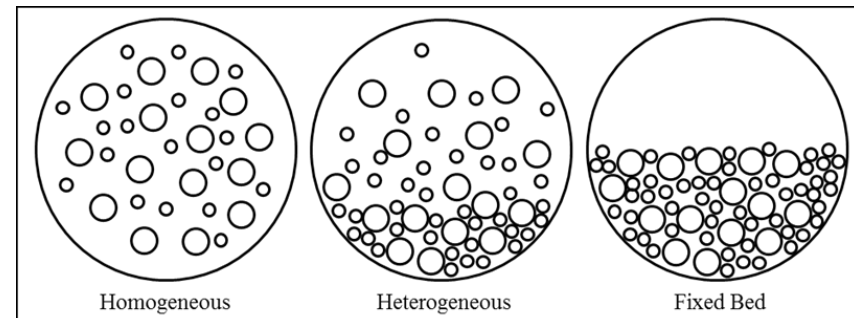
- Effect of screen opening shape
- Evaluate  $SG = f(\Omega, V_L)$

# SLURRY FLOW

## Cutter Suction Dredge



$$\frac{P_1}{\gamma} + \frac{V_1^2}{2g} + z_1 + h_p = \frac{P_2}{\gamma} + \frac{V_2^2}{2g} + z_2 + h_L$$





*Dwight Look College of*

**ENGINEERING**  
TEXAS A&M UNIVERSITY

# SLURRY FLOW

## Cutter Suction Dredge

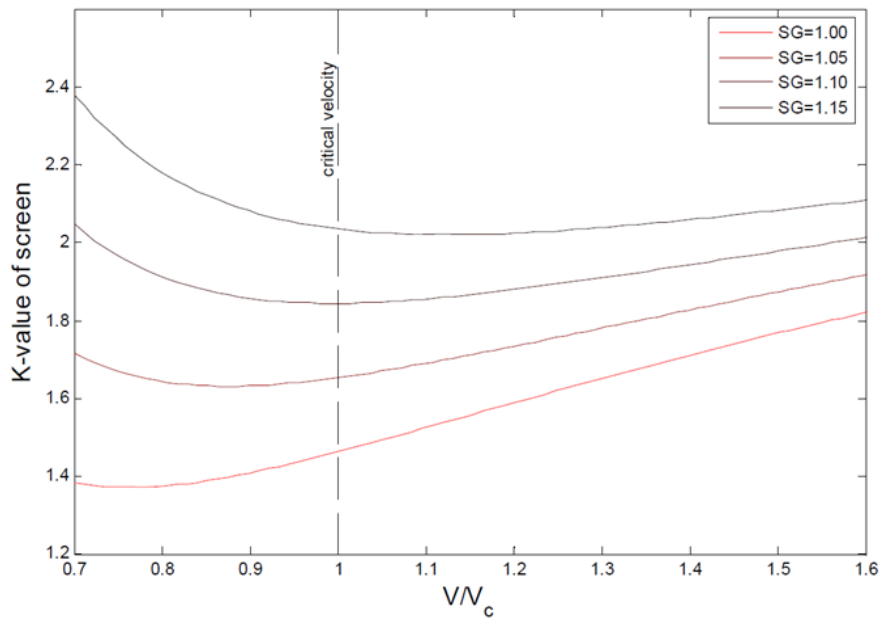


# Influence of Flow Rate and Specific Gravity

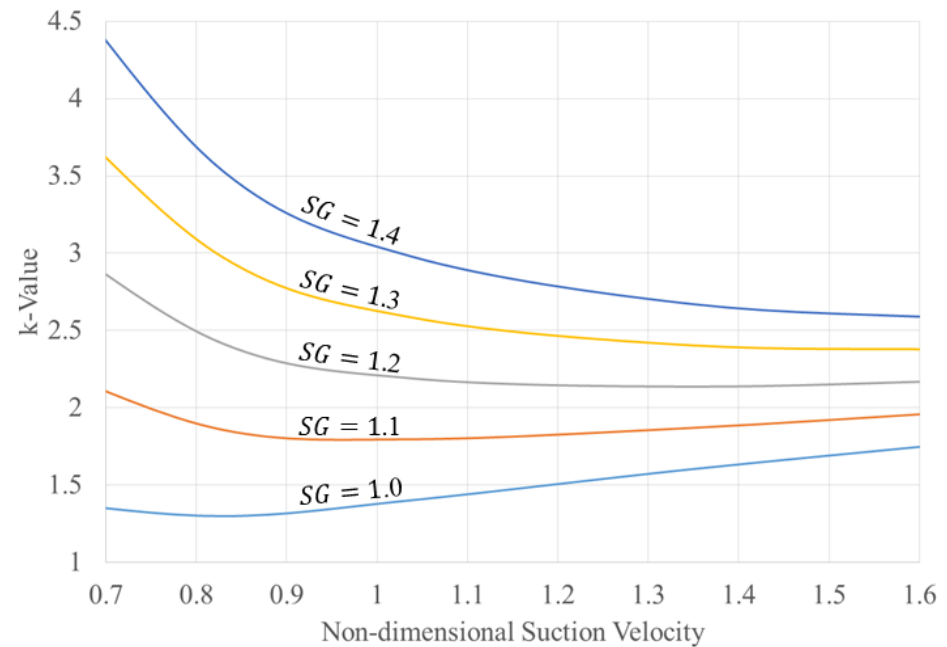
- Low flow rate:
  - Cutter head-dominant flow field
  - Significant spillage occurs (Steinbusch, et al., 1999)
    - 5 to 40% of total dredged material (Dekker, et al., 2003)
  - Low production
  - $\downarrow k$  (Girani, 2014)
- High flow rate:
  - Suction-dominant flow field
  - Less spillage ( $\uparrow$  SG)
  - Increased production (Henriksen, 2009)
  - $\uparrow k$

## Influence of Flow Rate and Specific Gravity

- Specific Gravity (SG) and Minor Loss Coefficient (k)



Girani (2014)

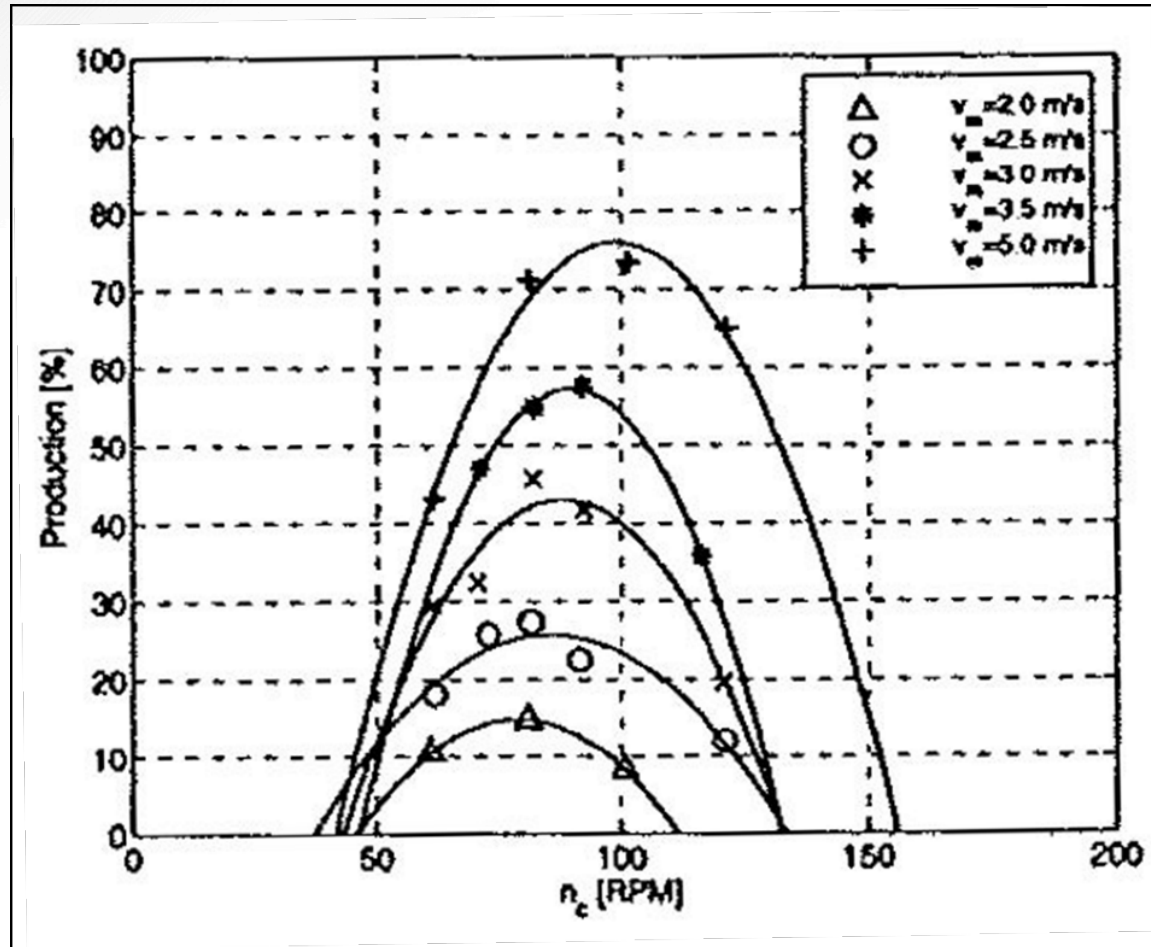


## Influence of Cutter Head Rotational Speed ( $\Omega$ )

- High Cutter Head Speeds:
  - Greater re-suspended sediment (Henriksen, et al., 2011)
  - Greater spillage (Hayes, et al., 2000)
  - Centrifugal force  $>$  (Gravitational Force + Drag Force) (den Burger, et al., 1999)
  - Reduced production
- Low Cutter Head Speed:
  - (Gravitational Force + Drag Force)  $>$  Centrifugal force (den Burger, et al., 1999)
  - Poor mixing (den Burger, et al., 1999)
  - Reduced production



## Influence of Cutter Head Rotational Speed ( $\Omega$ )



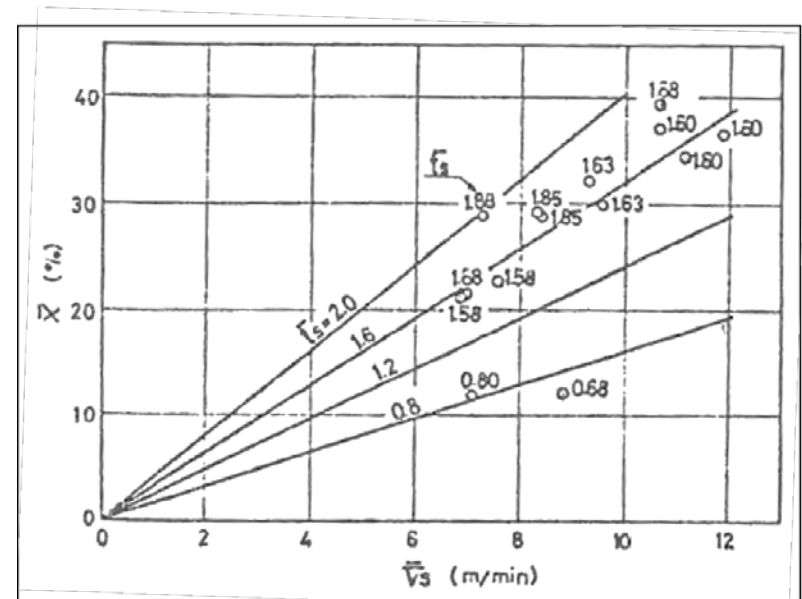
# Influence of Ladder Arm Swing Speed ( $V_L$ )

- Prediction Models (Hayes, et al., 2000):

- Dimensional Model: Spillage  $\downarrow$  when  $V_L \uparrow$
- Non-dimensional model: Spillage  $\uparrow$  when  $V_L \uparrow$

- Experiments (Yagi, et al., 1975):

- Mud Content in Pipeline  $\uparrow$  when  $V_L \uparrow$





# MODEL SCALING

Operating Parameter	Prototype	Haynes Lab Model Dredge	Model to Prototype Ratio
Cutter Head Rotational Speed	30 RPM	15 to 45 RPM	1:2 to 1: <sup>2</sup> / <sub>3</sub>
Cutter Head Diameter	60 in (152 cm)	16 in (40.6 cm)	~1:4
Cutting Thickness	30 in (76 cm)	10 in (25 cm)	1:3
Water Depth	40 ft (12.2 m)	8 ft (2.44 m)	1:5
Grain Size ( $d_{50}$ )	0.00164 ft (0.5 mm)	0.00090 ft (0.275 mm)	~1:2
Grain Settling Velocity*	0.207 ft/s (63 mm/s)	0.108 ft/s (33 mm/s)	~1:2
Discharge Pipe Diameter	30 in (76 cm)	3 in (0.076 m)	1:10
Ladder Arm Swing Speed	12 in/s (30 cm/s)	1.0 to 3.0 in/s (2.5 to 7.6 cm/s)	1:12 to 1:4
Flow Rate	30,000 GPM (113,550 l/min)	250 to 400 GPM (946 to 1514 l/min)	1:5 to 1:4

\*calculated using Schiller (1992) equation



# MODEL SCALING

Hydraulic Scaling  
(sediment pick-up behavior)

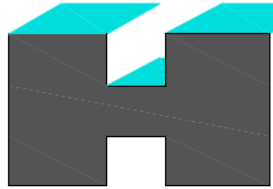
Glover (2002)

Kinematic Scaling  
(Froude Number)

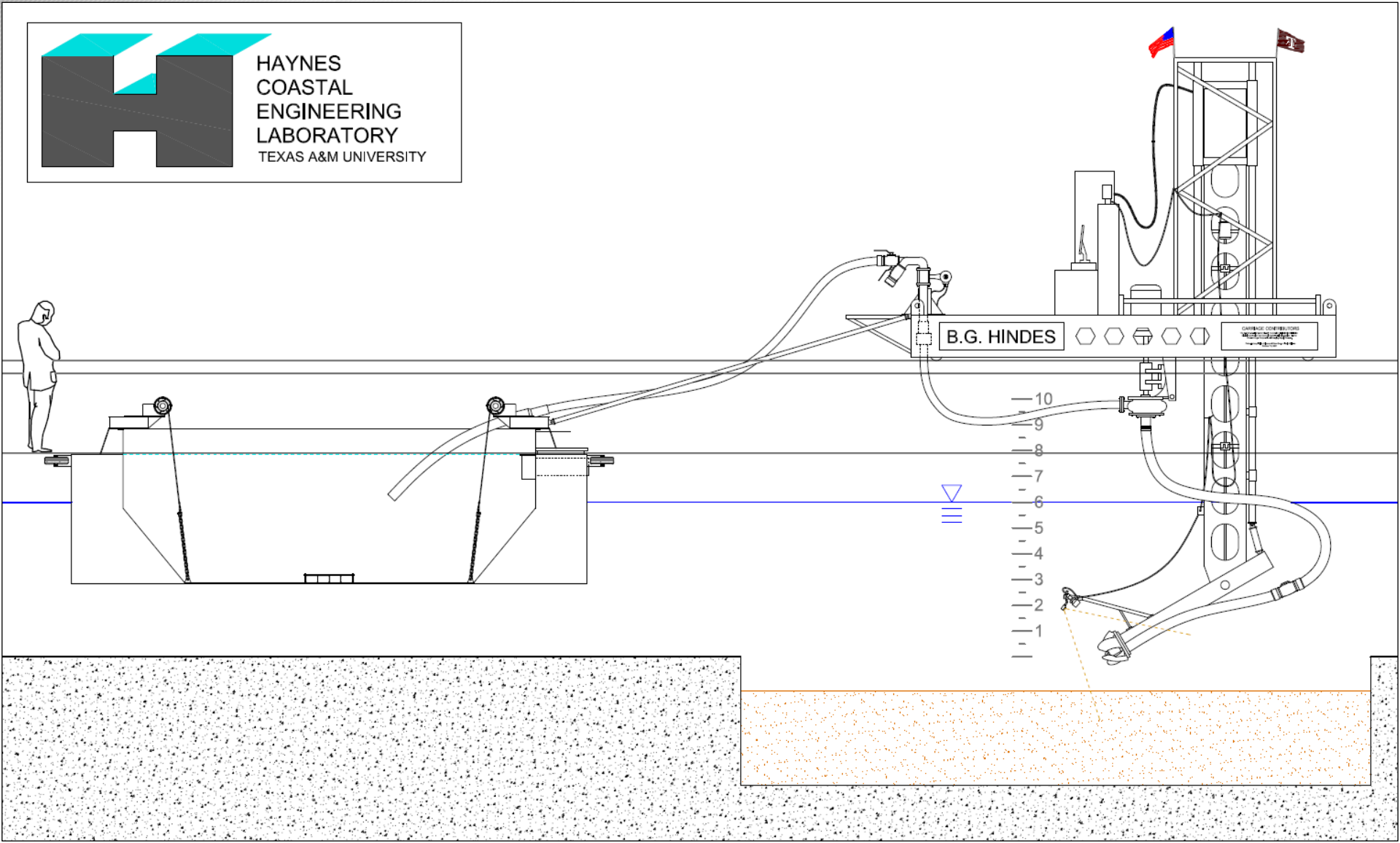
Parameter	Scaling Method			Chosen Test Parameters
	Hydraulic	Kinematic	Geometric (1:10)	
$Q_{\text{model}}$ (GPM)	1117	1102	30	250 to 400
$\Omega_{\text{model}}$ (rpm)	21	58	30	15 to 45
$(V_L)_{\text{model}}$ (in/s)	3.2	6.2	1.2	1.0 to 3.0



# TEST SETUP



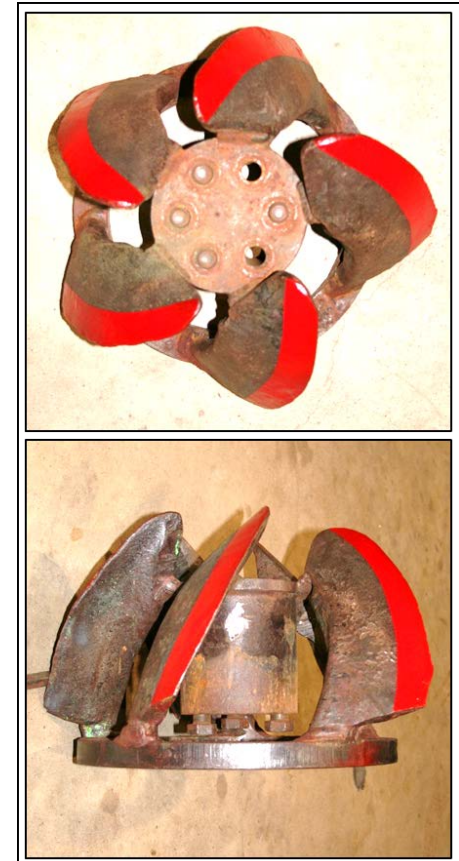
HAYNES  
COASTAL  
ENGINEERING  
LABORATORY  
TEXAS A&M UNIVERSITY



## Suction Inlet

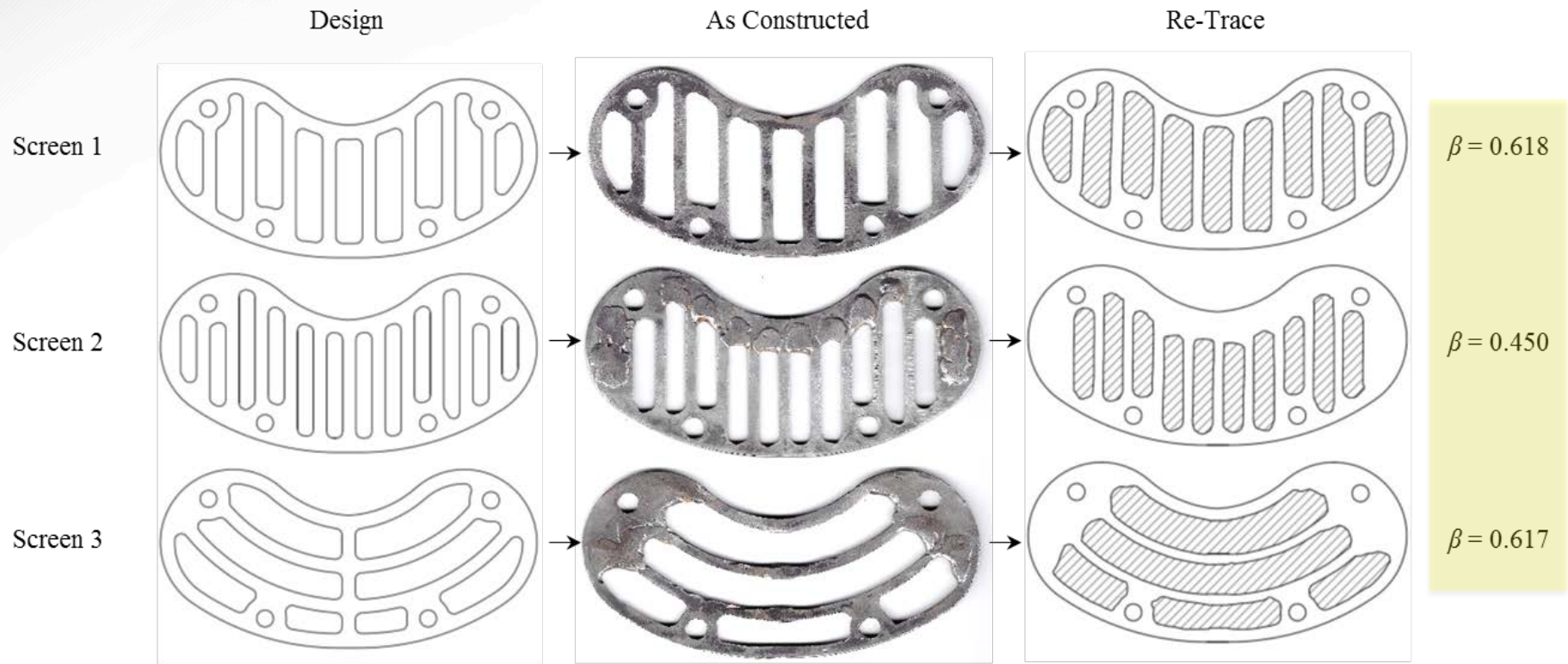


Total Opening Area = 14.0 in<sup>2</sup>



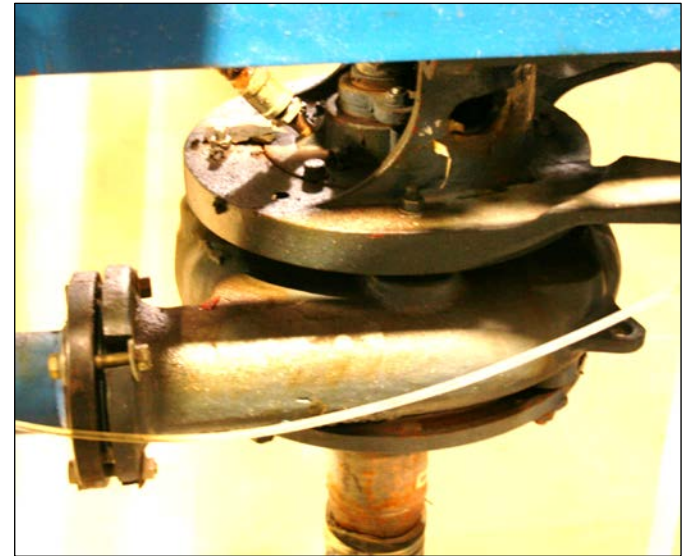
Diameter = 16 in

## Screens



# Centrifugal Pump

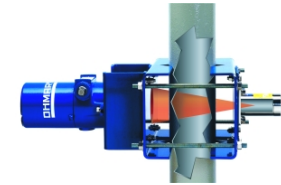
- Manually controlled
- $h_p = 20$  hp
- Max flow rate = 600 GPM
- Vane diameter = 12.2 in
- $P_s$  and  $P_d$  measured
- 3" discharge hose





## Sensors

- Ohmart GEN2000<sup>®</sup> nuclear density gauge



Ohmart (2014)

- Krohne IFC 090K electromagnetic flow meter



Krohne (1997)

- Rosemount 1511AP pressure transmitter

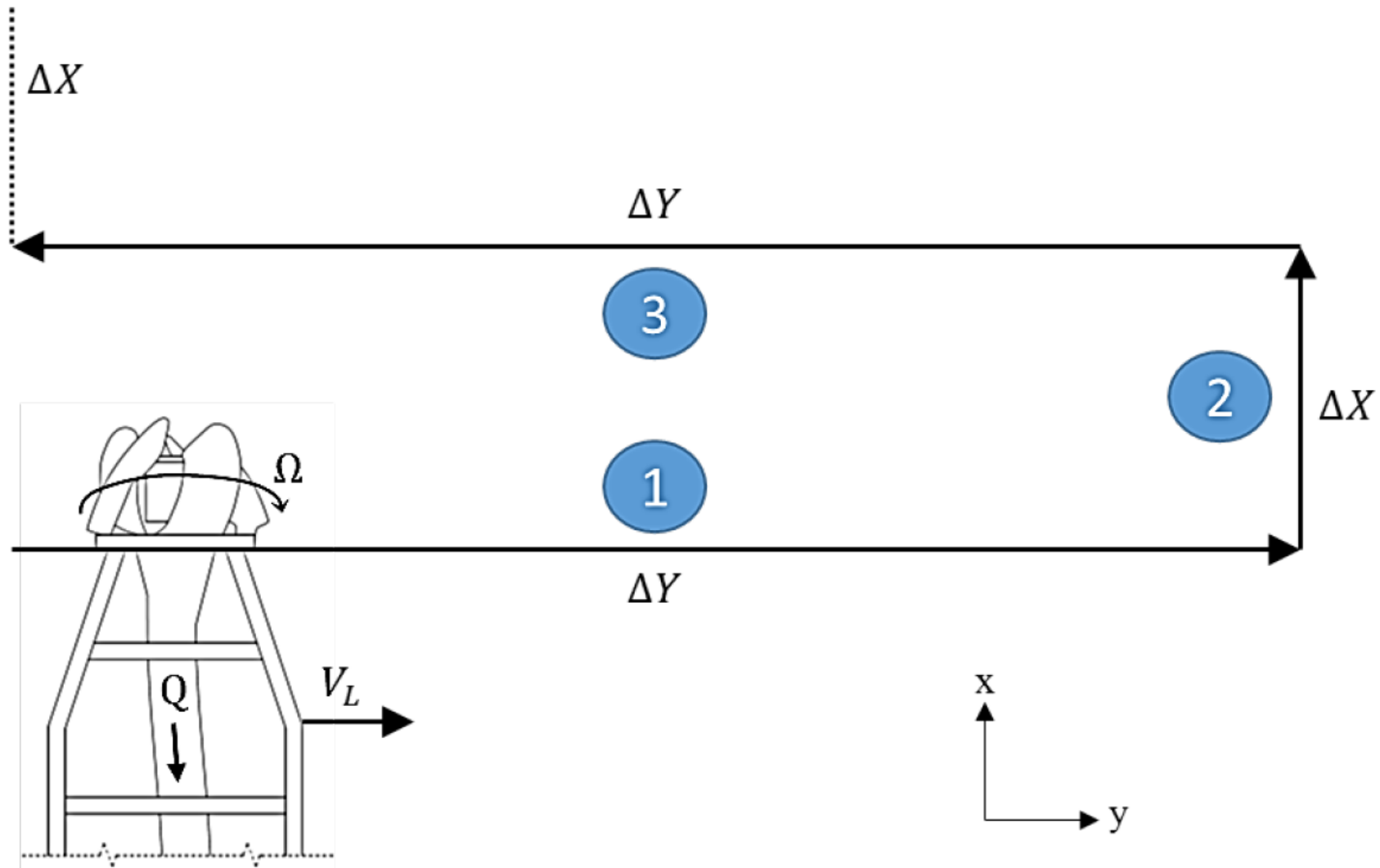


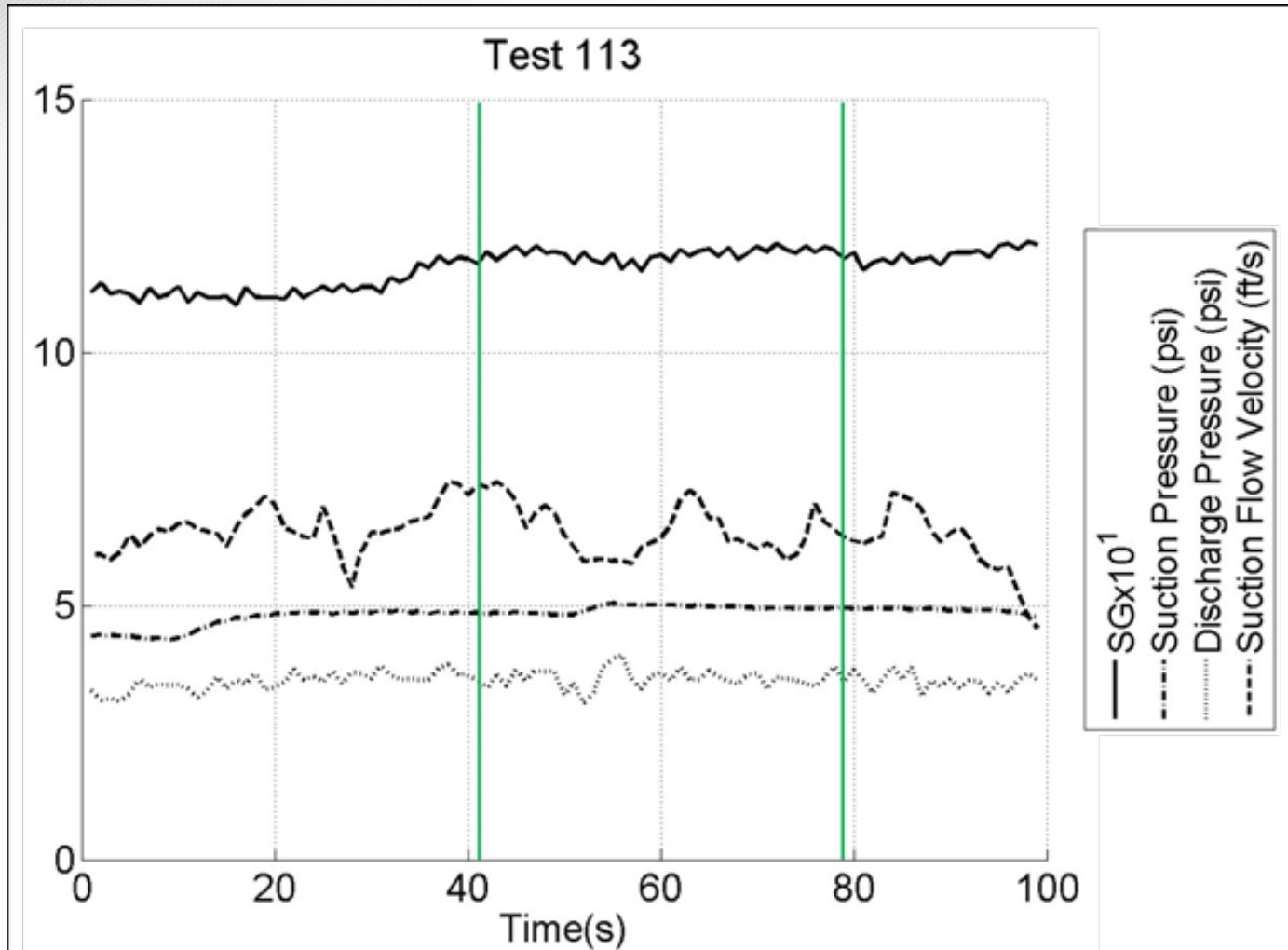
Rosemount, Inc. (2007)

- ToughSonic<sup>®</sup> distance sensor TS30S1-1V

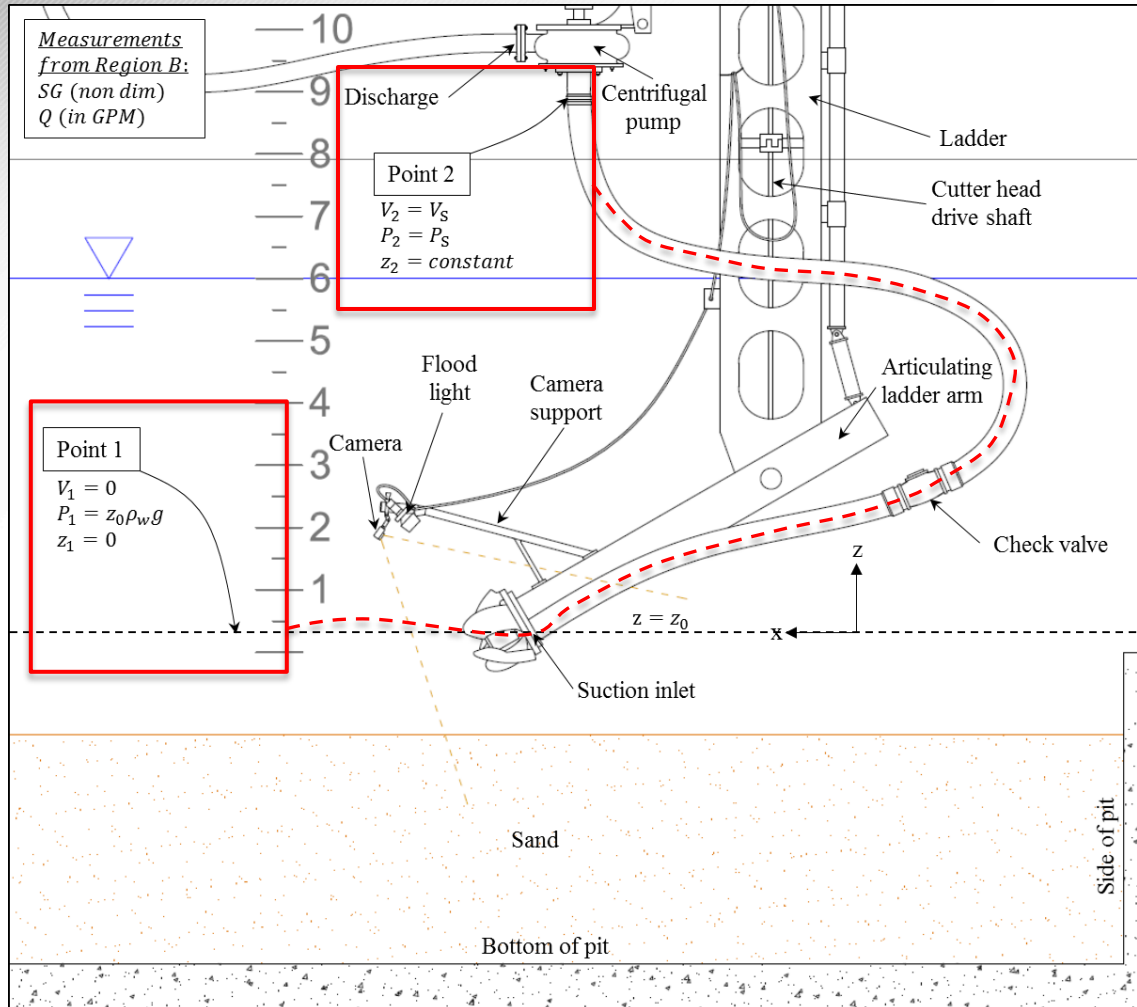


Senix Corporation (2007)





# CALCULATION OF K



## Conservation of Energy

$$\frac{P_1}{\gamma} + \frac{V_1^2}{2g} + z_1 + h_p = \frac{P_2}{\gamma} + \frac{V_2^2}{2g} + z_2 + h_L$$

## Evaluate at two conditions:

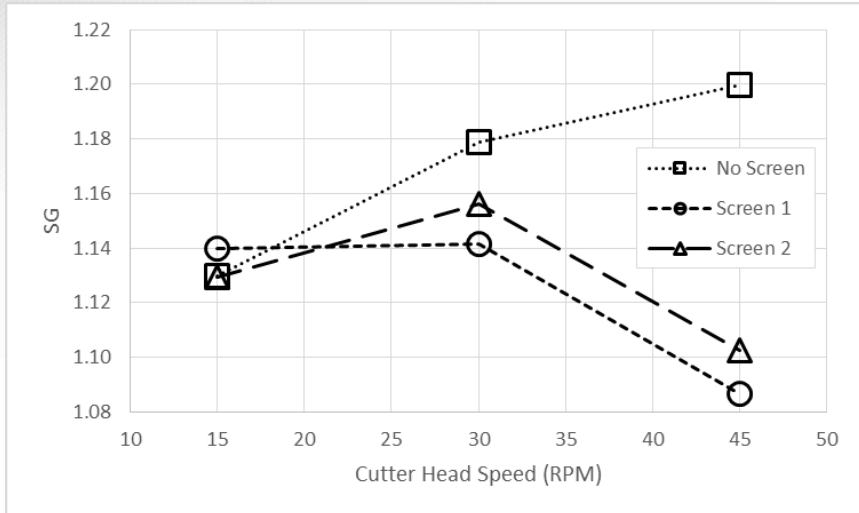
Screen ON	$\frac{P_{1n}}{\gamma} = \frac{P_{Sn}}{\gamma} + \frac{V_{2n}^2}{2g} + z_2 + h_{Ln}$
Screen OFF	$\frac{P_{10}}{\gamma} = \frac{P_{S0}}{\gamma} + \frac{V_{20}^2}{2g} + z_2 + h_{L0}$

$$\Delta h_{Ln}$$

## Calculate k

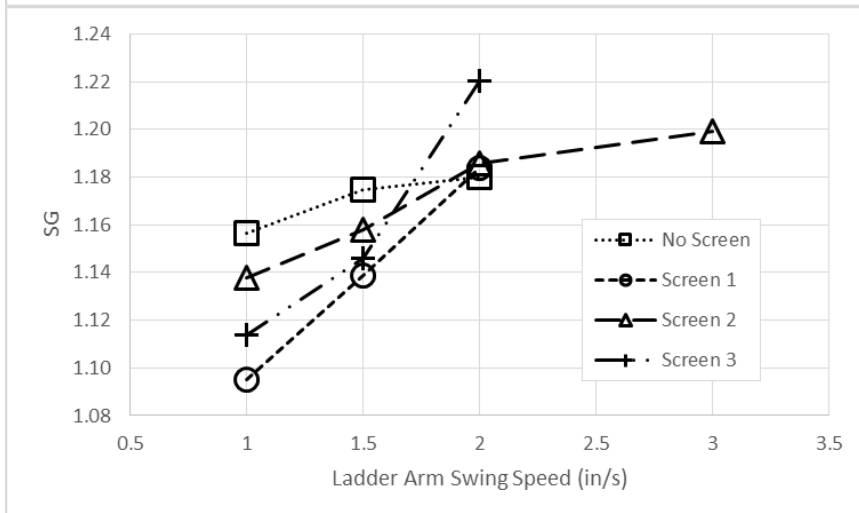
$$k_n = \Delta h_{Ln} \frac{2g}{V_S^2}$$

## Specific Gravity



### Cutter Head Speed Effect

- Optimum  $\Omega$  that maximizes **SG**



### Swing Speed Effect

- **SG**  $\uparrow$  as  $V_L$   $\uparrow$



## Cutter Head Effects – Spillage

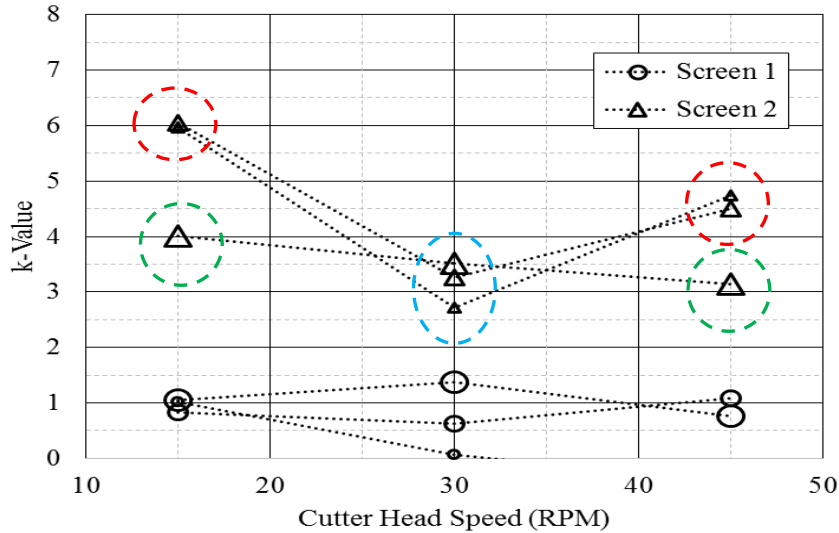


15 rpm

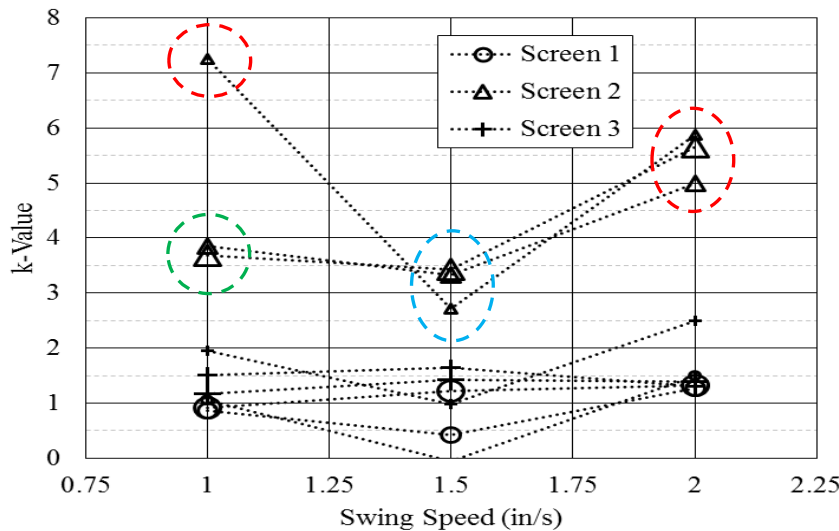
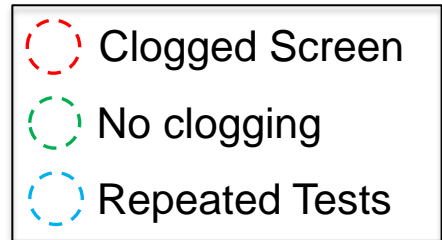
30 rpm

45 rpm

# RESULTS



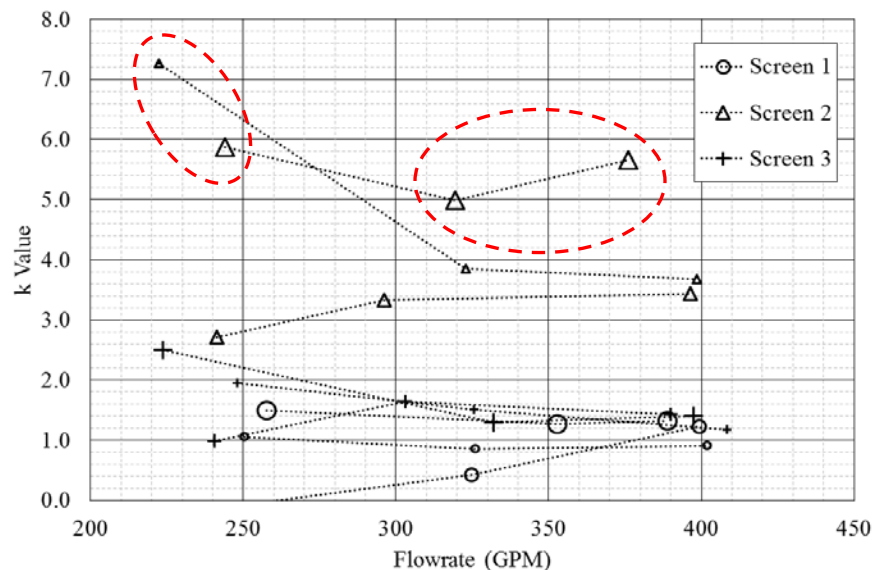
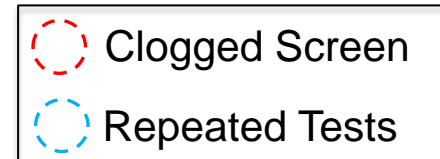
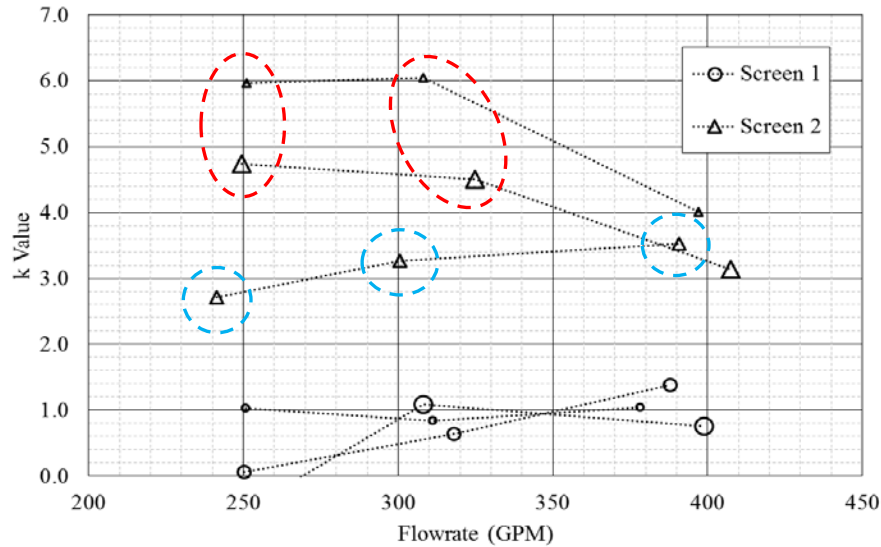
- No consistent **k-value** relationship with  $\Omega$



- No consistent **k-value** relationship with  $V_L$

## Slurry Tests

- No consistent **k-value** relationship with flow rate (for  $\Omega$  tests)
- **k-value convergence**



- No consistent **k-value** relationship with flow rate (for  $V_L$  tests)
- **k-value convergence**



# RESULTS

## Screen Opening Shape

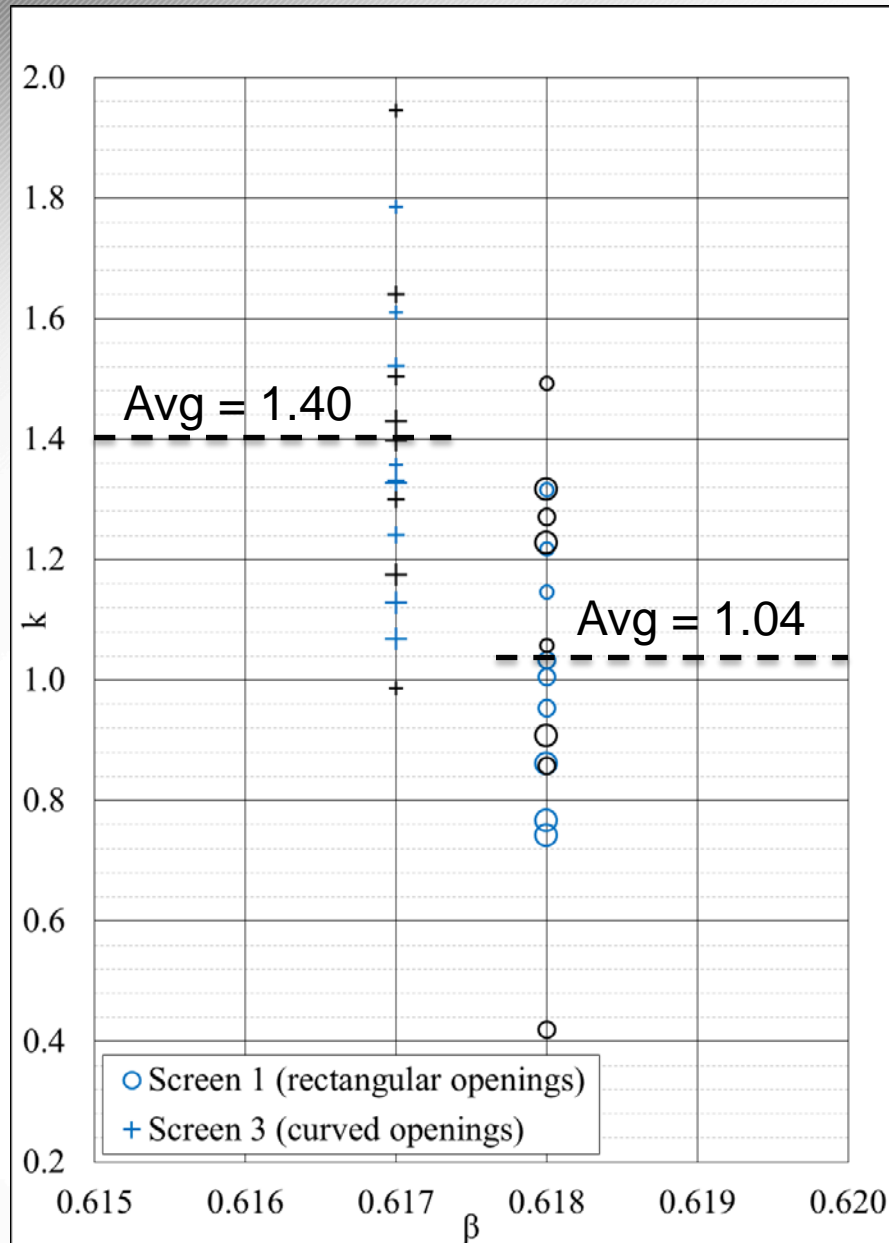
- Screen 1



- Screen 3



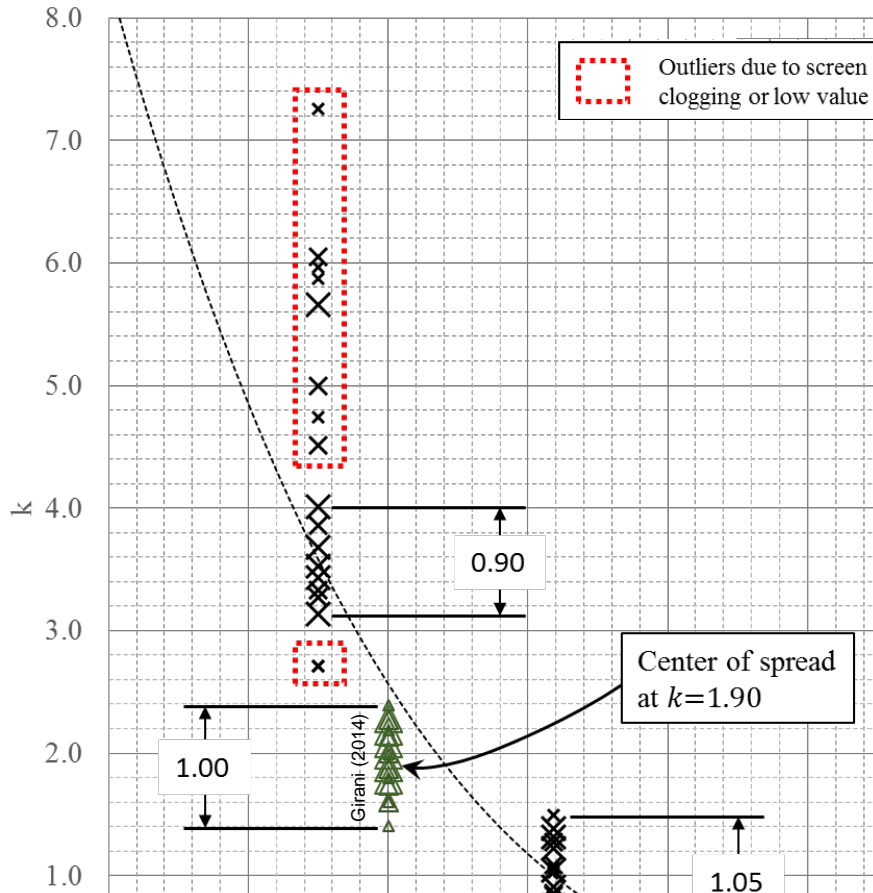
- **Greater average k-value for Screen 3**



# RESULTS

## k and $\beta$ – Slurry Tests

k-Value vs.  $\beta$



Manual Curve Fit

$$k(\beta) = 29(1 - \beta)^{3.5}$$

Girani (2014) Equation

$$\frac{2g}{V_S^2} \left( \begin{array}{l} -0.694 - 0.442 \cdot V_S + 1.302 \cdot SG \\ + 0.0468 \cdot V_S^2 + 0.187 \cdot V_S \cdot SG \end{array} \right)$$

**SG** and **V<sub>s</sub>** Correction Term

$$\frac{2g}{V_S^2} \left( \begin{array}{l} -0.694 - 0.442 \cdot V_S + 1.302 \cdot SG \\ + 0.0468 \cdot V_S^2 + 0.187 \cdot V_S \cdot SG \end{array} \right) - 1.90$$

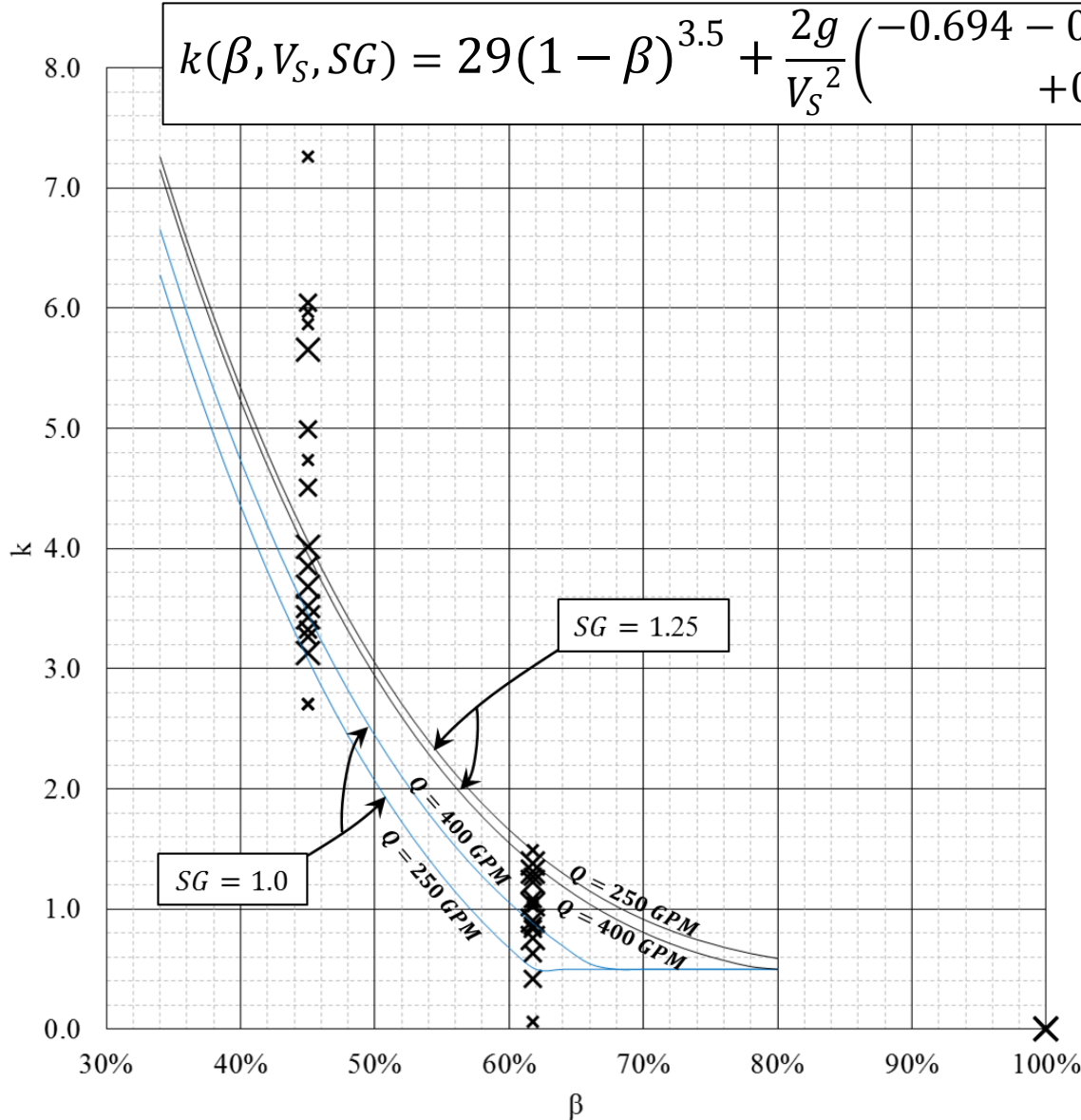
$$k(\beta, V_S, SG) = 29(1 - \beta)^{3.5} + \frac{2g}{V_S^2} \left( \begin{array}{l} -0.694 - 0.442 \cdot V_S + 1.302 \cdot SG \\ + 0.0468 \cdot V_S^2 + 0.187 \cdot V_S \cdot SG \end{array} \right) - 1.90$$

$\beta$

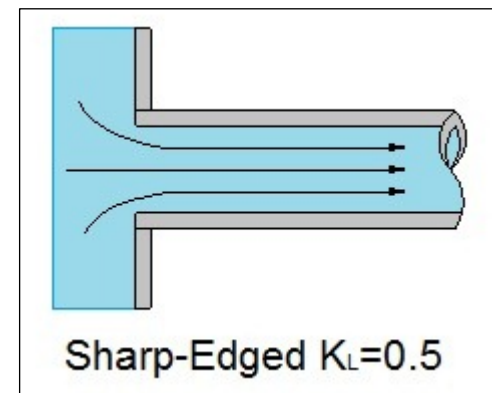
# RESULTS

## k and $\beta$ – Slurry Tests

$$k(\beta, V_S, SG) = 29(1 - \beta)^{3.5} + \frac{2g}{V_S^2} \left( \begin{array}{l} -0.694 - 0.442 \cdot V_S + 1.302 \cdot SG \\ +0.0468 \cdot V_S^2 + 0.187 \cdot V_S \cdot SG \end{array} \right) - 1.90$$



- Plotted over experimental data

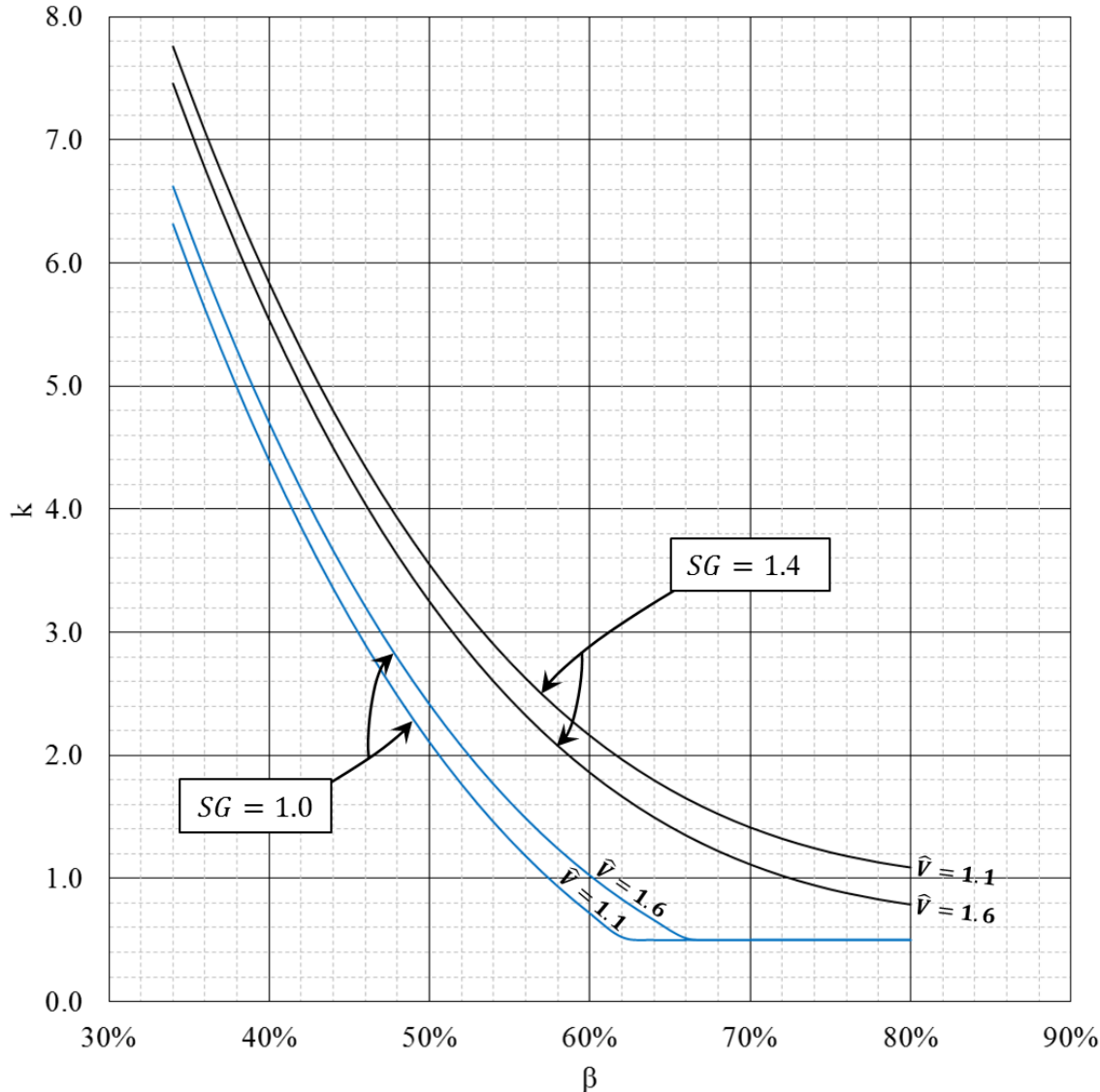


(Amirault, 2014)

# RESULTS

## k and $\beta$ – Slurry Tests

K-Value Prediction Curves



- Non-dimensional plot
- Extrapolated to common dredging parameters
- $1.1 \leq \hat{V} \leq 1.6$
- $1.0 \leq \mathbf{SG} \leq 1.4$
- Minimum k-value of 0.5

## Conclusion

- No direct correlation between screen **k-value** and  $\Omega$  or  $V_L$
- k-value increases exponentially with decreasing  $\beta$
- Screen opening shape may change the screen's inherent **k-value**
- k-values converge at high  $V_S$  and **SG**
- Screen clogging at Haynes Lab may occur at  $\beta < 0.50$

Girani (2014)

## Conclusion

- Spillage increases with  $\Omega$
- **SG** and production increase with  $V_L$
- Optimum  $\Omega$  exists ( $\Omega$  is limited by  $V_L$ )
- k-value prediction equation may be used for model or full-size dredges

Hayes, et al. (2000);  
Henriksen, et al. (2011)

Yagi, et al. (1975)

den Burger, et al.  
(1999)

- Future Experiments

- Larger range of  $\Omega$
- Larger range of  $V_L$
- More  $\beta$ -values
- Different screen opening shapes
  
- Take measures during testing to prevent screen clogging when  $\beta < 0.50$
- Investigate methods to prevent screen clogging
- Automated flow control of dredge pump



# PHOTOS





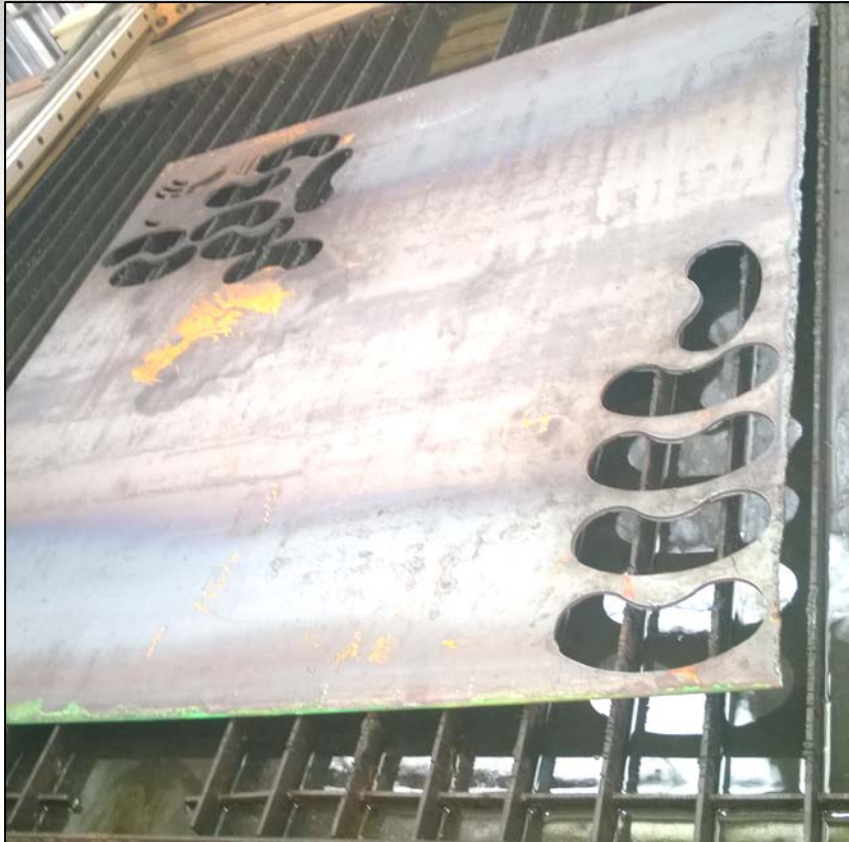


# PHOTOS





# PHOTOS





*Dwight Look College of*

**ENGINEERING**  
TEXAS A&M UNIVERSITY

# QUESTIONS?

LT Joshua M. Lewis

SPAWAR Systems Center Pacific, San Diego, CA

(619)553-6116

[joshua.m.lewis@navy.mil](mailto:joshua.m.lewis@navy.mil)